Lanyue Tang

Research Interest: Human-Machine Interaction, Artificial Intelligence, Autonomous Vehicle, and Traffic Simulation.

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EDUCATION

Tongji University *Shanghai, China*

Master of Transportation Planning and Management *Sep 2021 - present*

- Supervisor: Prof. Jian Sun and Assis. Prof. Lishengsa Yue
- GPA: 4.09/5

Southeast University *Nanjing, China*

Bachelor of Traffic Engineering *Sep 2017 – Jun 2021*

- GPA: 3.69/4

PUBLICATION

JOURNAL PUBLICATIONS:

Tang, L., Zhang, D., Han, Y., Tian, Y., Yue, L., Sun, J.* (2023), Parallel-Computing-Based Calibration for Microscopic Traffic Simulation Model, Transportation Research Record, Washington, DC.(IF=2.019)

Tang, L., Yue, L.*, Yuan, J., Sun, J., Fu, A. (2024), CPSOR-GCN: A Vehicle Trajectory Prediction Method Powered by Emotion and Cognitive Theory. (under second round of review of Journal of Intelligent Transportation Systems) (**IF = 3.839**)

Tian, Y, Fu, A., Zhang, H, **Tang L.**, Sun, J (2024) Accelerated Verification of Autonomous Driving Systems based on Adaptive Subset Simulation, IEEE Transactions on Intelligent Vehicles. (IF = 14)

CONFERENCE PUBLICATIONS:

Tang, L., Yue, L*, Fu, A. (2023), Interactive Vehicle Trajectory Prediction Considering Abnormal Emotion Based on SOR Cognitive Framework, 2023 7th CAA International Conference on Vehicular Control and Intelligence (CVCI), Oral Presentation.

Tang, L., Han, Y., Zhang, D., Tian, Y., Sun, J.* (2021), Parallel Computing-based Calibration for Microscopic Traffic Simulation Model, Transportation Research Board 101st Annual Meeting (TRB).

Liu, S., Zhang, Q., Wang, P., Feng, B., Huang, C., Zhang, Y., **Tang, L.**, Yue, L., Sun, J. (2023), Enhance SIL Simulation Through Driver Behaviour Modeling at Unprotected Left-turn Scenario for Autonomous Driving SOTIF Analysis, 2023 7th International Conference on Intelligent Traffic and Transportation (ICITT).

Fu, A., Zhang, H., **Tang, L.**, Tian, Y. * (2023), Accelerated Verification of Autonomous Driving Systems based on Subset Simulation, Transportation Research Board 103rd Annual Meeting (TRB).

PATENT:

Tang, L., Yue, L.*, Yuan, J., Sun, J., Fu, A., A Vehicle Trajectory Prediction Method Considering Driver's Abnormal Emotions. *Chinese Patent*, 2023 (**Submitted**).

RESEARCH Projects

Modeling the influence mechanism of emotions on driving behavior in pre-crash *Dec 2022 – Present*

scenarios for ADAS application

- Proposed a trajectory prediction method that takes into account drivers' abnormal emotions, aiming to solve the problem of false alarms in active safety systems.
- The model takes into account physical motion and cognitive characteristics, and its accuracy is confirmed through building and experimenting with driving simulator environments (based on UE4 and Carla).
- Built a trajectory prediction model (CPSOR-GCN) based on physical GCN, cognitive GCN and LSTM-attention.
- Significantly reduced prediction errors by extracting driver cognitive features, providing an effective means for improving Advanced Driver Assistance System(ADAS).

Calibration of lane-drop bottleneck micro simulation model accelerated by   *Jue 2021 –Jue 2022*
parallel computing

- Developed a microscopic traffic simulation calibration algorithm by applying parallel computing technology, which solved the problems of traditional heuristic algorithms that are time-consuming and inefficient.
- By building a simulation model based on SUMO and parallelizing the genetic algorithm and particle swarm optimization algorithm.
- The calibration time is shortened from 5 hours to less than 1 hour, and the calibration efficiency is increased by 80%.

Project: Driver Modelling and Scenario Generation – Huawei Technologies Co., Ltd.   *May 2022 – Sep 2023*
Core member

- Established a multi-style driver model of left-turn vehicle interaction at the intersection based on the actual collected trajectory data to meet the heterogeneity of drivers in the actual traffic environment.
- Deployed the established driver model in VTD simulation software and provided a test environment that can adjust the heterogeneity of traffic flow for the autonomous driving algorithm.

HONORS

- Outstanding Graduate Thesis of Tongji University   June 2024
- The 3rd Shanghai University Student Traffic and Transportation Science and Technology Competition – Linlong Lighting Cup   *Dec 2023*
- Outstanding Student of the Fifth Yinfu Class   *Mar 2023*
- "Zhixing Cup" Shanghai College Student Social Practice Competition, Third Prize   *Nov 2022*
- American College Student Mathematical Modeling Competition, Honourable Mention   *Mar 2020*
- YunYing Scholarship   *Oct 2019*

SKILLS

- Proficiency with Python and MATLAB.
- Proficient in Carla, Vissim, Sumo, VTD, UE4, and RoadRunner.
- Proficiency in PyTorch and TensorFlow possessing a strong grasp of deep learning and machine learning concepts, can address problems such as overfitting and gradient explosion.